

Babasaheb Bhimrao Ambedkar Bihar University, Muzaffarpur
Directorate of Distance Education
P.G. 3rd Semester Examination 2015 (Session 2014-16)
Subject:- Mathematics
Paper - 9th
Model Paper (Full Marks - 80)

Numerical Analysis

① what do you mean by difference of zero.

Calculate the values

$$\Delta^2 0.5, \Delta^2 0.8, \Delta^4 0.5$$

② Obtain Newton's forward difference formula for equal intervals.

③ state and prove

Fundamental Theorem on difference calculus.

④ Find the relation between operator E of finite difference and differential coefficients

⑤ D of differential calculus.

⑥ Define factorial notation

Prove that

$$\Delta^n x^{(m)} = n! h^m$$

and

$$\Delta^{n+1} x^{(n)} = 0$$

⑦ Prove the recurrence relation

$$\Delta^n 0^m = n \left[\Delta^{n-1} 0^{m-1} + \Delta^n 0^{m-1} \right]$$

⑧ obtain Newton's forward difference formula for equal intervals.

⑨

8) Define Leibnitz's rule. Use Leibnitz's rule for finding $\delta^3(2^x)$ if interval of differencing is h .

9. Find ~~the~~ and correct - by means of differences its errors with following table.

20736, 28561, 38416, 50625,
65540, 83521, 104976, 130321,
161000.

10) Discuss errors and their analysis

11) Represent the function $f(x) = x^4 - 12x^3 + 24x^2 - 30x + 9$ and its successive differences into factorial notation.

12) Find the function whose first-difference is $3x^2 + 11x + 5$.

13) Discuss Newton-Raphson Method.

14) Write comparison of Newton's method with its Regula. Falsi method

15) Discuss Graeffe's root squaring method

16) Apply Graeffe's method to find all the roots of the equation $x^4 - 3x + 1 = 0$

- 17) Obtain $\sqrt{12}$ to five places of decimals by Newton's Raphson method
- 18) Find the cube roots of 10
- 19) Discuss the bisection method. formulae.
- 20) Discuss the method of false position.
- 21) Discuss the iteration method
- 22) Write the Newton - Gregory formulae for ~~with~~ interpolation
- 23) Write ~~the~~ Newton - Gregory formulae for Backward interpolation.
- 24) Given $\text{Si } 45^\circ = .7071$,
 $\text{Si } 50^\circ = .7660$, $\text{Si } 55^\circ = .8192$,
 $\text{Si } 60^\circ = .8660$
 find $\text{Si } 52^\circ$ by using any method of interpolation.
- 25) Define divided difference. Divided difference are symmetric functions of their arguments i.e. the value of any divided difference is independent of the order of the argument. Prove this

(21) The n^{th} divided difference of a polynomial of the n^{th} degree are constant. Prove it.

(22) Show that the n^{th} divided difference can be expressed as the quotient of two determinants each of order $n+1$.

(23) The n^{th} divided difference can be expressed as the product of multiple integrals. Prove it.

(24) Discuss Newton's formulae for unequal intervals.

(25) Define Lagrange's interpolation formulae for unequal intervals.

(26) Obtain Newton's backward difference formulae.

(27) Using Newton's forward difference formula, find the

$$S_n = 1^3 + 2^3 + 3^3 + \dots + n^3$$

(28) Define Gauss's interpolation formulae.

31) Find the Lagrange interpolating polynomial of degree 2 approximating the function $y = \ln x$ defined by the following table of values

x	$y = \ln x$
2	0.69315
2.5	0.91629
3.0	1.09861

32) Define maxima and minima of a tabulated function.

33) Discuss General Quadrature Formula for Equidistant ordinates.

34) Establish Trapezoidal rule for numerical integration.

35) Obtain Simpson's one-third rule for numerical integration.

36) Obtain Simpson's three-eighths rule for numerical integration.

30 Obtain Weddle's Rule for numerical integration

31 Show that $\int_0^1 \frac{dx}{x} = \log 2 = .69315$

32 Obtain Homogeneous linear difference equation with constant coefficients

33 Solve

$$2y_{k+2} - 5y_{k+1} + 2y_k = 0$$

34 Solve

$$y_{k+1} - 2y_k = k+1$$

35 Define curve fitting. Discuss its principle of least square for curve fitting

36 Discuss the method of changing origin and scale for simplifying the calculations in the case of curve fitting.

37 Show that the linear difference equation of order n is given by

$$f_0(k) y_{k+n} + f_1(k) y_{k+n-1} + \dots + f_n(k) y_k = g(k)$$

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Subject:- Mathematics
Paper - 10th
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Functional Analysis

- (I) Define normed linear space with an example
- (II) Define Banach space with an example.
- (III) Construct a normed linear space which is not a Banach space
- (IV) Prove that C is a normed linear space E ,

$$\| \|z\| - \|y\| \| \leq \|z - y\|$$

- (V) Prove that C is a normed linear space vector addition, norm and scalar multiplication are continuous functions
- (VI) Let T be a linear transformation of a normed linear space N into another linear space N' . Then show that the following

statements are equivalent to one another.

(i) T is continuous

(ii) T is continuous at the origin

(iii) There exists a real number $K > 0$ such that

$$\|T(x)\| \leq K \|x\|, \forall x \in E$$

(iv) If $S = \{x : \|x\| \leq 1\}$ is the closed unit sphere in E , then the image $T(S)$ is a bounded set in E' .

(v) If E and E' be normed linear spaces and let T be a linear transformation of E into E' , then the ~~inverse~~ inverse T^{-1} exists and is continuous on its domain of definition iff there exists a constant $m > 0$ such that

$$m \|x\| \leq \|T(x)\|, \forall x \in E$$

(vi) Prove that for any normed linear space E , the identity transformation

$I: E \rightarrow E$ defined by

$$I(x) = x, \forall x \in E$$

is a continuous linear transformation.

(9) Let N or N' be normed linear spaces with the same scalars and $B(N, N')$ the set of all bounded linear operators $T: N \rightarrow N'$, then $B(N, N')$ is a normed linear space with respect to the pointwise linear operations and the norm defined by

$$\|T\| = \sup_{\|f\| \leq 1} \|T(f)\|$$

Further if N' is a Banach space then $B(N, N')$ is also a Banach space.

(10) Let M be a closed linear subspace of a normed linear space N and let T be the natural mapping of N onto N/M defined by $T(f) = f + M$. Then T is a continuous linear transformation for which

$$\|T\| \leq 1.$$

(11) Every n -dimensional linear space $L(F)$ is isomorphic to F^n .

(12) Define Dual space of a linear space.

(13) Show that every finite dimensional linear space is algebraically reflexive.

(14)

Normed space $C[a, b]$

(15) Let N or N' be normed linear space over the same scalar field and let T be a linear transformation of N into N' . Then T is bounded iff it is continuous.

(16)

Let N be a normed linear space and let $S = \{x \in N : \|x\| \leq 1\}$ be a linear space of N .

Prove that N is a Banach space

$\Leftrightarrow S$ is complete

(17)

Define equivalence

norm

(18) Let a linear space E be made into a normed linear space in two ways and let the two norms on a vector x be denoted by $\|x\|$ or $\|x\|'$ then the two norms generate the same topology on E iff \exists two positive numbers m and M s.t.

$$m\|x\| \leq \|x\|' \leq M\|x\|$$

$\forall x \in E$

18) Stab- or prove
Hahn-Banach theorem

19) Stab- or prove
Open mapping theorem

20) Stab- or prove closed
graph theorem

21) Stab- or prove
Banach-Steinhaus
theorem
or
The principle of
Uniform boundedness.

22) Define Inner product-spaces
and Hilbert-space with
Schauder example

23) Stab- or prove
Schwarz inequality

24) Prove that in
Hilbert-space the
product is jointly
continuous

25) If x and y are any
two vectors in a Hilbert
space then

26) $\|x+y\|^2 + \|x-y\|^2 = 2\|x\|^2 + 2\|y\|^2$

27) $4\|x\|^2\|y\|^2 = (\|x\|^2 - \|y\|^2)^2 + (\|x+y\|^2 - \|x-y\|^2)^2$

26) Let \mathcal{R} be a complex Banach space whose norm obeys the parallelogram law and if an inner product is defined on \mathcal{R} by

$$4\langle x, y \rangle = \|x+y\|^2 - \|x-y\|^2 + i(\|x+iy\|^2 - \|x-iy\|^2), \quad \forall x, y \in \mathcal{R}$$

\mathcal{R} is a Hilbert space

27) Define convex set. A closed convex subset C of a Hilbert space H contains a unique vector of smallest norm.

28) Start our proof
Cauchy-Schwarz-Bunyakowsky inequality

29) Every finite dimensional linear inner product space is separable. Prove this

30) Start our proof
Pythagorean theorem

31) Define orthogonal complement.

32) Let M be a linear subspace of a Hilbert space H . Show that M is closed $\Leftrightarrow M = M^{\perp\perp}$

(32)

State and prove the Projection Theorem on a Hilbert space.

(34)

The orthogonal complement of a subspace is itself a subspace.

(35)

Define orthonormal set

(36)

State and prove

Bessel's inequality

(37)

Show that two Hilbert spaces having the same dimension are isomorphic

(38)

Prove that

$$\|f\| - \|g\| \leq \|f - g\|$$

(39)

Define Complete orthonormal set

(40)

State and prove Gram-Schmidt orthogonalization process in a Hilbert space

(41)

Prove that an orthonormal set in a Hilbert space is linearly independent

(42)

State and prove the Riesz-Representation theorem for continuous linear functionals on a Hilbert space.

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Partial differential
 Equations

- ① Discuss Lagrange's method of solving the quasi linear partial differential equations of order one

$$P(x, y, z) \frac{\partial z}{\partial x} + Q(x, y, z) \frac{\partial z}{\partial y} = R(x, y, z)$$

- ② Find the condition for the equations

$$f(x, y, z, p, q) = 0$$

$$\text{or } g(x, y, z, p, q) = 0$$

to be compatible.

- ③ solve

④ solve $px + qy = z$

⑤ solve $y^2 p - xyq = z(z - 2y)$

$$xz p + yz q = xy$$

(6) Along every strip of the P.D.E

$F(x, y, z, p, q) = 0$ the function $F(x, y, z, p, q)$ is constant. Prove this

(7) Find the characteristics of the P.D.E

$$p^2 + q^2 = 2$$

and determine the integral surfaces which pass through

$$x=0, z=y.$$

(8) Find the complete integral of $(p^2 + q^2)z = 2z^2$

(9) Define surface orthogonal to a given system of surfaces.

(10) Define compatible system of first order equations.

(11) Discuss the Charpit's method for solution of non-linear P.D.E of first order.

(12) Define Jacobi method for solution of non-linear P.D.E of order one with more than three independent variables.

(13) Explain Cauchy's method or characteristic

(14) Discuss method of finding the complementary function of the linear homogeneous P.D.E with constant coefficients

(15) Solve

$$(D^2 + 3DD' + 2D'^2)z = x + y$$

(16) Solve

$$(2D^2 - 5DD' + 2D'^2)z = 5 \sin(2x + y)$$

(17) Classify the linear P.D.E of second order and reduce it into canonical forms and discuss briefly the elliptic, parabolic and hyperbolic form

(18) Find the characteristic of the equation

$$u_{xx} + 2u_{xy} + \sin^2(x)u_{yy} + u_y = 0$$

When it is of hyperbolic type.

(19) Classify and transform the following equation to a canonical form

(20) Transform the following differential equation to a canonical form

$$u_{xx} + 2u_{xy} + 4u_{yy} + 2u_x + 3u_y = 0$$

(27) Reduce

$$\frac{\partial^2 z}{\partial x^2} = 2x \left(\frac{\partial z}{\partial y} \right) +$$

Canonical form

(29) Write the Transport Equation for a linear hyperbolic system.

(29) Discuss derivation of one dimensional wave equation

(29) Discuss derivation of two dimensional wave equation

(27) Discuss derivation of one - dimensional ~~heat~~ heat equation.

(28) Explain the Laplace's equation in spherical

Coordinates

(27) Define Harmonic function. If a harmonic function vanishes everywhere on the boundary, then it is identically zero everywhere.

(28) Discuss the separation of variables

(29) Find the general solution of one-dimensional wave equation

$$\frac{\partial^2 \gamma}{\partial x^2} = \left(\frac{1}{c^2}\right) \left(\frac{\partial^2 \gamma}{\partial t^2}\right)$$

(30) Discuss D'Alembert's solution of one dimensional wave equation

(31) Obtain Green's function for the wave equation.

(32) Determine the Green's function for the Helmholtz equation for the half space $z > 0$.

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Paper - XII
Analytical Dynamics

1. Define the following terms:
 - (a) Generalised coordinates
 - (b) degree of freedom
 - (c) Holonomic system and Non-Holonomic system
 - (d) Conservative and Non-Conservative system.
2. Derive Lagrange's equation of motion of a system of particle with given generalised coordinates.
 - (a) Set up the Lagrangian for a simple pendulum and obtain an equation describing its motion.
 - (b) Obtain the Lagrangian equation of motion for a double pendulum vibrating plane.
 - (c) Show that the K.E is a holonomic dynamical system in a quadratic function of velocities.

- (6) deduce the principles energy from the Lagrange's equation (conservative field)
- (7) Use Lagrange's equation to find differential equations for a compound pendulum which oscillates in a vertical plane about a fixed horizontal axis
- (8) obtain the Lagrange's equation with impulsive forces
- (9) obtain the Lagrange's equations for non-holonomic system with moving constraints
- (10) A particle of mass m moves under the influence of gravity on the inner surface of the paraboloid of revolution $x^2 + y^2 = az$ which is assumed frictionless. Obtain the equations of motion.
- (11) Before phase space, obtain Hamilton's canonical equations
- (12) If the Hamiltonian H is independent of t explicitly prove that it is:
 - a constant and is
 - Equal to the total energy of the system.

- 13) State and prove Brachistochrone problems
- 14) Discuss the Hamilton's variational principle
- 15) obtain derivation of Hamilton's equations from the variational principle
- 16) Discuss the principle of least action.
- 17) write distinction between Hamilton's principle and the principle of least action.
- 18) use the variational method to show that the shortest curve joining two fixed points is a straight line.
- 19) Prove that the shortest distance between two points on the surface of the sphere is the arc of the great circle connecting them.
- 20) obtain Lagrange's equation from Hamilton's principle.
- 21) write the Hamiltonian and equations of motion for a simple pendulum.
- 22) obtain Euler's equation from Hamilton's equation.

- (23) Use Hamilton's equations to find the equations of motion of a projectile in space.
- (24) Use the variational method to show that the shortest curve joining two fixed points is a straight line.
- (25) Discuss the stationary property of normal modes in the theory of small oscillation.
- (26) Define point- and canonical transformations and obtain the transformation equations.
- (27) Obtain the conditions that a transformation from (q, p) basis to (Q, P) basis be canonical.
- (28) Define Lagrange's bracket. Also show that invariance of Lagrange's bracket is a condition for canonical transformations.
- (29) Define Poisson bracket. Show that the Poisson bracket of two dynamical variables u and v under canonical transformation is invariant.
- (30) Write relation between Lagrange's and Poisson brackets.

- (30) Obtain Hamilton - Jacobi equation for a holonomic system given by the canonical equations
- (31) Obtain Hamilton - Jacobi equation for Hamilton's characteristic function
- (32) Explain how Hamilton - Jacobi equation can be used to solve Kepler's problem for a particle in an inverse square central force field.
- (33) Discuss Harmonic oscillator problem as an example of the Hamilton Jacobi method
- (34) Obtain the Hamiltonian and Hamilton's equation for a charged particle, in an electromagnetic field.
- (35) A particle of mass m moves in a force field of potential V .
- write the Hamiltonian and
 - Hamilton's equation in Cartesian coordinates.
- (36) Use Hamiltonian equation to find the equation of motion of a projectile in space

(37) Find the equation of motion of a simple pendulum

(38) Discuss the simple Harmonic oscillator

(39) Obtain K.E of rigid body with a fixed point.

(40) Obtain Euler's equation from Lagrange equation

(41) Prove that the contact transformation possesses the group property. Also define subgroups of Matrices transformation and extended Poincaré transformation.
